

矩阵求导（多元线性回归）

$$\bar{v} = X\bar{w} + \bar{b} = \begin{pmatrix} x_{11} & x_{12} & \dots & x_{1d} \\ x_{21} & x_{22} & \dots & x_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nd} \end{pmatrix}_{n \times d} * \begin{pmatrix} w_1 \\ w_2 \\ \dots \\ w_d \end{pmatrix}_{d \times 1} + \begin{pmatrix} b \\ b \\ \dots \\ b \end{pmatrix}_{n \times 1} = \begin{pmatrix} \sum_{j=1}^d x_{1j} * w_j + b \\ \sum_{j=1}^d x_{2j} * w_j + b \\ \dots \\ \sum_{j=1}^d x_{nj} * w_j + b \end{pmatrix}_{n \times 1}$$

首先对X扩充一列：

$$X = \begin{pmatrix} x_{11} & x_{12} & \dots & x_{1d} \\ x_{21} & x_{22} & \dots & x_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nd} \end{pmatrix}_{n \times d} \Rightarrow \begin{pmatrix} x_{11} & x_{12} & \dots & x_{1d} & 1 \\ x_{21} & x_{22} & \dots & x_{2d} & 1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nd} & 1 \end{pmatrix}_{n \times (d+1)} = \begin{pmatrix} \bar{x}_1 & 1 \\ \bar{x}_2 & 1 \\ \dots & \dots \end{pmatrix}_{n \times (d+1)}$$

扩充一列后的 X

b加入到 w 中，增加一行得到**新的**：

$$\bar{w} = \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_d \end{pmatrix}_{d \times 1} \Rightarrow \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_d \\ b \end{pmatrix}_{(d+1) \times 1} = \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_d \\ w_{d+1} \end{pmatrix}_{(d+1) \times 1}$$

扩充w为更简单形式

这样的话：

$$\bar{v} = X\bar{w} = \begin{pmatrix} x_{11} & x_{12} & \dots & x_{1d} & 1 \\ x_{21} & x_{22} & \dots & x_{2d} & 1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nd} & 1 \end{pmatrix}_{n \times (d+1)} * \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_d \\ w_{d+1} \end{pmatrix}_{(d+1) \times 1} = \begin{pmatrix} \sum_{j=1}^{d+1} x_{1j} * w_j \\ \sum_{j=1}^{d+1} x_{2j} * w_j \\ \dots \\ \sum_{j=1}^{d+1} x_{nj} * w_j \end{pmatrix}_{n \times 1} = \begin{pmatrix} \sum_{j=1}^d x_{1j} * w_j + b \\ \sum_{j=1}^d x_{2j} * w_j + b \\ \dots \\ \sum_{j=1}^d x_{nj} * w_j + b \end{pmatrix}_{n \times 1}$$

和西瓜书格式一样了

求解目标也转化为通过loss关于新的（包含以前的 w 和 b）的导数为零的极值点：

$$\frac{1}{n} \frac{\partial \|\bar{y} - \bar{v}\|^2}{\partial \bar{w}} = 0 \Rightarrow \frac{1}{n} \frac{\partial \|\bar{y} - X\bar{w}\|^2}{\partial \bar{w}} = 0$$

$$loss = \|\bar{y} - X\bar{w}\|^2 = (\bar{y} - X\bar{w})^T (\bar{y} - X\bar{w})$$

$[x_{i1}, x_{i2}, \dots, x_{id}]$ 表示一个行向量，故 $[x_{i1}, x_{i2}, \dots, x_{id}]^T$ 是一个列向量。

$$loss = \|\bar{y} - X\bar{w}\|^2 = (\bar{y} - X\bar{w})^T (\bar{y} - X\bar{w}) = (\bar{y}^T - \bar{w}^T X^T)(\bar{y} - X\bar{w})$$

$$\Rightarrow loss = \bar{y}^T \bar{y} - \bar{y}^T X\bar{w} - \bar{w}^T X^T \bar{y} + \bar{w}^T X^T X\bar{w}$$

$$\frac{\partial loss}{\partial \bar{w}} = \frac{\partial \|\bar{y} - X\bar{w}\|^2}{\partial \bar{w}} = \frac{\partial (\bar{y}^T \bar{y} - \bar{y}^T X\bar{w} - \bar{w}^T X^T \bar{y} + \bar{w}^T X^T X\bar{w})}{\partial \bar{w}} = 0$$

$$\Rightarrow \frac{\partial \bar{y}^T \bar{y}}{\partial \bar{w}} - \frac{\partial \bar{y}^T X\bar{w}}{\partial \bar{w}} - \frac{\partial \bar{w}^T X^T \bar{y}}{\partial \bar{w}} + \frac{\partial \bar{w}^T X^T X\bar{w}}{\partial \bar{w}} = 0$$

所以loss对 \bar{w} 求导转化为了以上四个式子对 \bar{w} 求导。

常用的矩阵求导公式(采用分子布局的矩阵求导公式):

下面的式子中小写字母a表示标量a，带横线的小写字母 \bar{a} 表示列向量，大写字母A表示矩阵，a, \bar{a} 和A都不是x或 \bar{x} 的函数。

需要记住 下面的求导公式，就像记住高中常见的求导公式一样。

$$(c1) \frac{\partial \bar{a}}{\partial x} = \bar{0} \quad (\bar{0} \text{ 是与 } \bar{a} \text{ 相同规模的列向量})$$

$$(c2) \frac{\partial a}{\partial \bar{x}} = \bar{0}^T \quad (\bar{0}^T \text{ 是与 } \bar{x} \text{ 相同规模的行向量})$$

$$(c3) \frac{\partial a}{\partial X} = \mathbf{0}^T \quad (\mathbf{0}^T \text{ 是与 } X \text{ 相同规模的矩阵})$$

$$(c4) \frac{\partial \bar{a}}{\partial \bar{x}} = \mathbf{0} \quad (\mathbf{0} \text{ 是矩阵})$$

$$(c5) \frac{\partial \bar{x}}{\partial \bar{x}} = I \quad (I \text{ 是单位矩阵})$$

下面的几个最重要：

下面的式子中小写字母 a 表示标量 a ，带横线的小写字母 \bar{a} 表示列向量，大写字母 A 表示矩阵， a ， \bar{a} 和 A 都不是 x 或 \bar{x} 的函数。

$$(c6) \frac{\partial \bar{a}^T \bar{x}}{\partial \bar{x}} = \frac{\partial \bar{x}^T \bar{a}}{\partial \bar{x}} = \bar{a}^T$$

$$(c7) \frac{\partial \bar{x}^T \bar{x}}{\partial \bar{x}} = 2\bar{x}^T$$

$$(c8) \frac{\partial (\bar{x}^T \bar{a})^2}{\partial \bar{x}} = 2\bar{x}^T \bar{a} \bar{a}^T$$

$$(c9) \frac{\partial A \bar{x}}{\partial \bar{x}} = A$$

$$(c10) \frac{\partial \bar{x}^T A}{\partial \bar{x}} = A^T$$

$$(c11) \frac{\partial \bar{x}^T A \bar{x}}{\partial \bar{x}} = \bar{x}^T (A + A^T)$$

所以：

$$(1) \frac{\partial \bar{y}^T \bar{y}}{\partial \bar{w}} = \bar{0}^T, \text{ 因为 } \bar{y}^T \bar{y} \text{ 和 } \bar{w} \text{ 无关}$$

$$(2) \frac{\partial \bar{y}^T X \bar{w}}{\partial \bar{w}} = ?$$

$$\text{根据公式 (c6)} \quad \frac{\partial \bar{a}^T \bar{x}}{\partial \bar{x}} = \frac{\partial \bar{x}^T \bar{a}}{\partial \bar{x}} = \bar{a}^T$$

$$\text{可知 } \bar{y}^T X \text{ 就是公式c6的 } \bar{a}^T, \text{ 故 } \frac{\partial \bar{y}^T X \bar{w}}{\partial \bar{w}} = \frac{\partial (\bar{y}^T X) \bar{w}}{\partial \bar{w}} = \bar{y}^T X$$

$$(3) \frac{\partial \bar{w}^T X^T \bar{y}}{\partial \bar{w}} = ?$$

$$\text{根据公式 (c6)} \quad \frac{\partial \bar{a}^T \bar{x}}{\partial \bar{x}} = \frac{\partial \bar{x}^T \bar{a}}{\partial \bar{x}} = \bar{a}^T$$

$$\text{可知: } X^T \bar{y} \text{ 就是公式里的 } \bar{a}, \quad \frac{\partial \bar{w}^T X^T \bar{y}}{\partial \bar{w}} = (X^T \bar{y})^T = \bar{y}^T X$$

$$(4) \frac{\partial \bar{w}^T X^T X \bar{w}}{\partial \bar{w}} = ?$$

$$\text{根据公式 (c11): } \frac{\partial \bar{x}^T A \bar{x}}{\partial \bar{x}} = \bar{x}^T (A + A^T)$$

可知 $X^T X$ 就是公式c11里的A:

$$\frac{\partial \bar{w}^T X^T X \bar{w}}{\partial \bar{w}} = \bar{w}^T (X^T X + (X^T X)^T) = \bar{w}^T (X^T X + X^T X) = 2\bar{w}^T X^T X$$

综上所述:

$$\frac{\partial loss}{\partial \bar{w}} = \frac{\partial \bar{y}^T \bar{y}}{\partial \bar{w}} - \frac{\partial \bar{y}^T X \bar{w}}{\partial \bar{w}} - \frac{\partial \bar{w}^T X^T \bar{y}}{\partial \bar{w}} + \frac{\partial \bar{w}^T X^T X \bar{w}}{\partial \bar{w}} = 0$$

$$\Rightarrow \frac{\partial loss}{\partial \bar{w}} = \bar{0}^T - \bar{y}^T X - \bar{y}^T X + 2\bar{w}^T X^T X = 2\bar{w}^T X^T X - 2\bar{y}^T X = 0$$

大功告成!

多元线性回归或者最小二乘法（最小平方法）的解为：

$$2\bar{w}^T X^T X - 2\bar{y}^T X = 0 \Rightarrow \bar{w}^T X^T X = \bar{y}^T X$$

等号两边同时转置得： $\bar{w}^T X^T X = \bar{y}^T X \Rightarrow X^T X \bar{w} = X^T \bar{y}$

所以可得： $\bar{w} = (X^T X)^{-1} X^T \bar{y}$ ，这就是多元线性回归的解。

来源：<https://zhuanlan.zhihu.com/p/146478349>